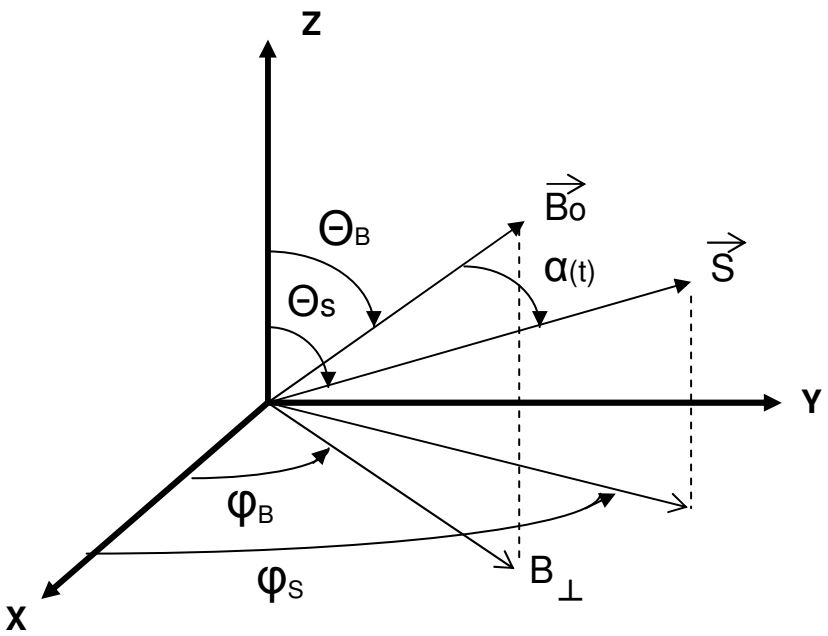

Z
$\vec{B_o}$
Θ_B
$\alpha(t)$
$\vec{S}$
Θ_S
Y
φ_B
φ_S
$B_\perp$
X